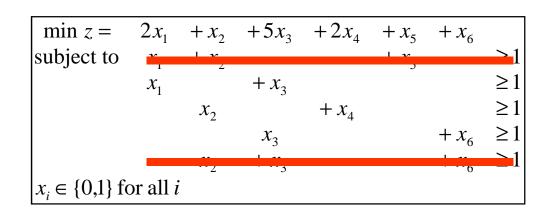
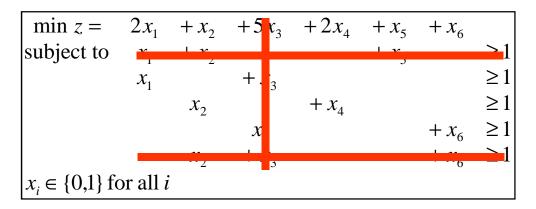
Consider This Set Covering Problem

I claim I can solve this by inspection

Now I Start Throwing Things Away ...



The first and last constraints are redundant – why?



x3 can be set to 0 - why?

Answer: $x_1 = 1$, $x_2 = 1$, $x_6 = 1$, z = 4

Presolve and Node Reductions

- An important feature of commercial codes is presolve
 - Looks at problem structure, particularly binary variables
 - Uses various techniques to reduce the problem
 - Can be applied at any node in a branch-and-bound tree
- These techniques are responsible for much recent improvement in MIP codes
- Following is a (partial) set of rules for cover (>=) and partition (=) problems
 - Note: can covert a pack to a partition by adding slack variables
 - Then, use the rules for a partition
 - These rules assume the C_i 's are all > 0

Reduction Rules

• (1) (cover, partition): If all A_{ij} 's are 0 in row i, the problem's infeasible

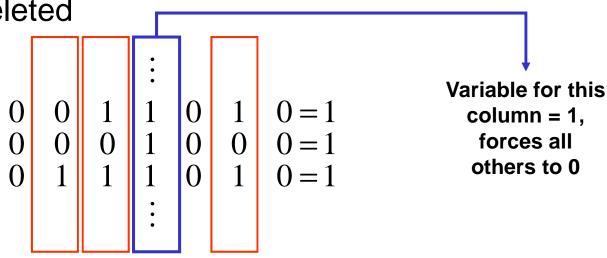
cover
$$0 \ 0 \ 0 \ 0 \ 0 \ \ge 1$$
 partition $0 \ 0 \ 0 \ 0 \ 0 \ = 1$

• (2)(cover, partition) If row i has 1 nonzero A_{ij} (say, A_{ik}), then set $x_{ik} = 1$, delete column k, and delete all rows r with $A_{rk} = 1$

OR 541 Fall 2009 Lesson 11-1, p. 4

More Reduction Rules

• (2a) (partition) In addition to the row deletions in (2), delete every column where $A_{tj} = A_{tk} = 1$, j <> k, for every row r deleted

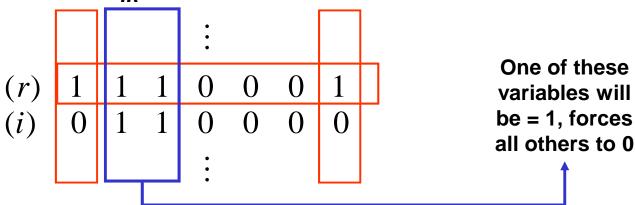


(3) (cover, partition) If A_{rj} >= A_{ij} for all j for rows r and i, delete row r

$$(r)$$
 $\begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 & 1 \\ i) & 0 & 1 & 1 & 0 & 0 & 0 & 0 \end{bmatrix}$

Yet More Reduction Rules

• (3a) (partition) As in (3), but also delete all columns with $A_{rk} = 1$ and $A_{ik} = 0$



• (4) (cover, partition) If S is a set of columns, and

$$\sum_{j \in S} A_{ij} = A_{ik} \text{ for all } i,$$

$$k \notin S, \text{ and } \sum_{i \in S} C_i \leq C_k$$

then, delete column k

Last of the Reductions

Reduction (4):

Reduction (4a) (cover) as in (4), but with condition

$$\sum_{j \in S} A_{ij} > A_{ik} \text{ for all } i$$

Example: Winston p. 477, ex. 5 (cover)

row 1	1	1	0	0	0	0
row 2	1	1	0	0	0	1
row 3	0	0	1	1	0	0
row 4	0	0	1	1	1	0
row 5	0	0	0	1	1	1
row 6	\cap	1	\cap	\cap	1	1

Rule 3: Delete row 2 (covered by row 1)

Rule 3: Delete row 4 (covered by row 3)

Example (cont'd)

No more reductions, but can you solve the problem?

•
$$x_2 = 1$$
, $x_4 = 1$

Strong Versus Weak Formulations

- An example from my past:
 - Job was associated with an airlift analysis
 - Had 100 possible onload locations in the U.S.
 - Needed to reduce locations to 10-20; all cargo from other locations would go to one of the chosen "hubs"
 - Wanted to minimize total tonnage*distance to move cargo to hubs
 - Known as a "k-median" problem
- First used a heuristic on the problem
- Was learning GAMS at the time, so I set it up as an integer program

The First K-Median Formulation

- Indicies
 - *i,j* = locations
- Data
 - **STONS**_i = short tons to be moved from location *i*
 - DIST_{ii} = distance between i and j
 - **MAXHUBS** = maximum number of hubs
 - **NUM** = total number of locations
- Variables
 - $assign_{ij} = 1$ if location i assigned to hub j, 0 otherwise
 - $choose_j = 1$ if location j chosen as a hub, 0 otherwise

The First Model

Objective and constraints:

$$\min z = \sum_{ij} DIST_{ij} * STONS_i * assign_{ij}$$
 what do these constraints do?
$$\sum_{i} assign_{ij} = 1 \text{ for all } i$$
 What does this constraint do?
$$\sum_{j} choose_{j} \leq MAXHUBS \leftarrow constraint do?$$

$$\sum_{i} assign_{ij} \leq NUM * choose_{j} \text{ for all } j \leftarrow choose_{j} \in \{0,1\} \text{ for all } i,j$$
 choose $j \in \{0,1\} \text{ for all } j$

No Luck

- Tried to solve this in OSL
 - Still didn't meet integrality gap requirements after 100,000 iterations
 - Ran for several hours
 - No progress
 - Went back to heuristic, wondered what I did wrong
- Asked an optimization professor a year later at a meeting
 - He sent back an answer the next day
 - His change allowed OSL to solve the problem in about 10 seconds
 - What was it?

A Stronger Formulation

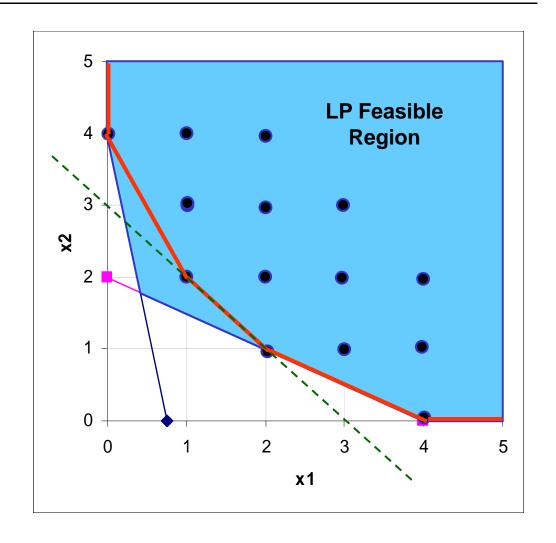
All he suggested was the following:

```
\min z = \sum_{ij} DIST_{ij} * STONS_{ij} * assign_{ij}
\text{subject to}
\sum_{j} assign_{ij} = 1 \text{ for all } i
\sum_{j} choose_{j} \leq MAXHUBS
assign_{ij} \leq choose_{j} \text{ for all } i, j
assign_{ij} \in \{0,1\} \text{ for all } i, j
choose_{j} \in \{0,1\} \text{ for all } j
```

- Note that this increased the number of constraints by 100 x 100 - 100 = 9900
- How could it be so much faster?

With MIPs, More Constraints Are Better

- The first formulation encouraged "fractionation" of the binary variables
- The second cuts off many possible fractional solutions
- Want to get as close to the "integer hull" as possible



Another Strengthening Example

• From the mining example:

```
o_{it} \ge o_{i,t+1} for all i, t < 5

e.g.,

o_{i1} \ge o_{i2}

o_{i2} \ge o_{i3}

\vdots
```

A stronger set of constraints:

```
o_{it} \ge o_{i,t'} for all i, t < 5, t' > t

e.g.,

o_{i1} \ge o_{i2}

o_{i1} \ge o_{i3}

o_{i1} \ge o_{i4}

o_{i1} \ge o_{i5}

o_{i2} \ge o_{i3}

\vdots
```

Cuts

- See Winston, Sec. 9-8
- Note that branching requires solving two LPs
 - One for the integer floor of the branching variable
 - One for the integer ceiling of the branching variable
- An alternative approach is called a cut
 - The idea here is to "cut off" the fractional solution, but don't cut off any feasible integer solutions
 - The aim is to generate constraints that form the integer hull of the feasible region
 - Such constraints are called *facets*

From the Dual Simplex Lesson (6-1)

Recall this was the optimal (fractionated) tableau:

Row	Z	x1	x2	s1	s2	RHS	BV
0	1	0	0	2/5	9/5	44/5	Z
1		1	0	-2/5	1/5	4/5	x1
2		0	1	1/5	-3/5	8/5	x2

Row 2 can be written as:

$$x_2 + \frac{1}{5}s_1 - \frac{3}{5}s_2 = \frac{8}{5}$$

• In Lesson 6-1, I used this row (called a *source row*) to generate a mysterious constraint; how did I do that?

Generating a Gomory Cut

 We rewrite this constraint by recognizing that any fraction can be written as

$$x = \lfloor x \rfloor + f, 0 < f < 1$$

So, applying this to Row 2, we get:

$$x_2 + \left(0s_1 + \frac{1}{5}s_1\right) + \left(-s_2 + \frac{2}{5}s_2\right) = \left(1 + \frac{3}{5}\right)$$

 Now, group the integral terms on the left and the fractional terms on the right:

$$x_2 + 0s_1 - s_2 - 1 = -\frac{1}{5}s_1 - \frac{2}{5}s_2 + \frac{3}{5}$$

Part we would like to get rid of

Some Arguments

- For integer feasibility:
 - The left-hand side must be integer
 - Therefore, the right-hand side must be integer
 - s_1 and s_2 must be >= 0
- So, what's the biggest the right-hand side can be and still be feasible?
- Result: we add the cut:

$$-\frac{1}{5}s_1 - \frac{2}{5}s_2 + \frac{3}{5} \le 0, \text{ or}$$
$$-\frac{1}{5}s_1 - \frac{2}{5}s_2 + s_3 = -\frac{3}{5}$$

• Is this cool, or what?

More Info on Cuts

- Cutting plane algorithms had a bad reputation early
 - Algorithms only added one cut at a time
 - Had very slow convergence
- Have recently become very popular
 - No reason to add cuts one at a time
 - Can add a cut for virtually any fractional row
 - Can combine with branch-and-bound (branch on one variable, generate cuts for others)
 - Easy to implement, run very quickly
- Bixby article shows that installing these cuts in CPLEX gives tremendous improvements

A (Very) Quick Tour of CPLEX MIP Switches

- For a small MIP or one known to be easy, you can stick with the defaults
- For anything else, you should always set the following:
 - Time limit (p. 95): CPLEX has a huge default (100,000,000 hours, a bit longer than I'd wait)
 - MIP strategy (p. 98): choose depth-first to emphasize feasibility, others to search for better solutions
 - Upper cutoff/lower cutoff (p. 106): *if you have a solution*, set these to avoid unproductive parts of the b-b tree
 - Relative/absolute gap (p. 106): a good starting relative gap is 0.10; absolute gap depends on the problem

CPLEX Switches You Can Play With

- Bound strengthening, coefficient reduction (p. 90)
 - These are more aggressive prereduce options
 - You should consider them if you have lots of binary variables and "chains" of relationships
- MIP probing (p. 99)
 - Explores implications of binary settings at every node
 - Time consuming, but may crack the problem early
- Variable selection (p. 99)
 - Strong branching is "probing lite" can be very helpful
 - Maximum infeasibility branching is useful if you have feasible solutions and want to get faster improvement

CPLEX Cuts

- CPLEX can employ 9 different types of cuts
 - Some are easy (like Gomory fractional cuts)
 - Some involve substantial math (disjunctive cuts)
 - Not easy to figure out a priori which will work
- Some general advice
 - CPLEX is fairly intelligent on when to apply cuts
 - If you're really having trouble, go aggressive on everything (kitchen sink approach)
 - Bixby's article gives good statistics on general performance of cuts on a large suite of MIPs
 - Clique cuts good for partition problems; cover cuts good for covers
 - Implied bound cuts good for problems with lots of general integer variables

Conclusion

- Be prepared for a lot of work with a big MIP
 - Exploit as much problem structure as you can
 - Use strong formulations; when in doubt, add more constraints
 - Help the solver with cutoff values and branch priorities
 - First get a feasible answer, then work from there
- Once you're feasible, work on improvement
 - Throw more switches to drive down the integrality gap
 - Recognize that some problems have "loose" LP formulations and require very long b-b solves to tighten the gap
 - Pay close attention to the structure of the interim feasible solutions
 - Add more constraints if you see opportunities (like the NOSWOT problem)

Constraint-Satisfaction Problems (CSPs)

- Sometimes we just want to find a feasible solution
- Map-coloring problem:
 - assign colors to maps so no adjacent countries have the same color
- Stable marriage problem
 - Have a group of N men, and a group of N women
 - Each woman has rated the men 1-N, as have each of the men
 - Assign men to the women so that if Man A prefers Man B's wife, Man B's wife prefers her husband to Man A
- Scene labeling
 - Recognize 3-D objects by assigning lines in 2-D drawings

The Idea of Constraint Programming

- Basic algorithm
 - You have a set of variables, each with a finite domain
 - You have a set of constraints that determine allowable settings on combinations of variables
 - Successive applications of those constraints reduce the domains of the variables
 - Stop when you come up with variable settings that satisfy all constraints
- Several commercial products, such as ILOG's OPL, provide a language for constraint programming

Integer Programming for CSPs

- In some cases, we can write integer programs to solve CSPs
- Consider SuDoKu
 - Problems consist of a 9 x 9 grid
 - Have to assign numbers 1-9 so that each row, column, and the 9 3 x 3 subgrids contains each number exactly once
- How do you solve these manually?
- Chances are, you use your own version of constraint programming

The Challenge

- Formulate an integer program in MPL to solve the SuDoKu problem shown to the right
- Furthermore, SuDoKu puzzles are advertised to have a single solution
- Does this one have a single solution? Modify your formulation to find out

					1		I	
7		3		1				
	6		8	4		3		
		5					8	
						2		8
	2		1				6	
6		9						
	5					1		
		6		3	5		4	
				2		7		9