

in 1797 Lagrange published in Paris his treatise on the Theory of Analytic Functions. In this fundamental book, he clearly describes his method for the solution of constrained optimization problems:

“...when a function of several variables has to be **minimized** or maximized, and there are one or more **equations** in the variables, it will be sufficient to add **the given function** and the functions that must equal zero, **each one multiplied** by an indeterminate quantity, **and then to look** for the maximum or the minimum **as if the variables** were independent; the equations **that will be found**, together with the given equations, **will serve for determining** all the unknowns.”

## Constraints optimization : Equality Constraints

$$f(x) \rightarrow \min$$

$$g(x) = 0$$

### *Lagrangian and Lagrange Multipliers*

$$L(x, \lambda) = f(x) - \lambda g(x)$$

$$\nabla_x L(x, \lambda) = \nabla f(x) - \lambda \nabla g(x) = 0$$

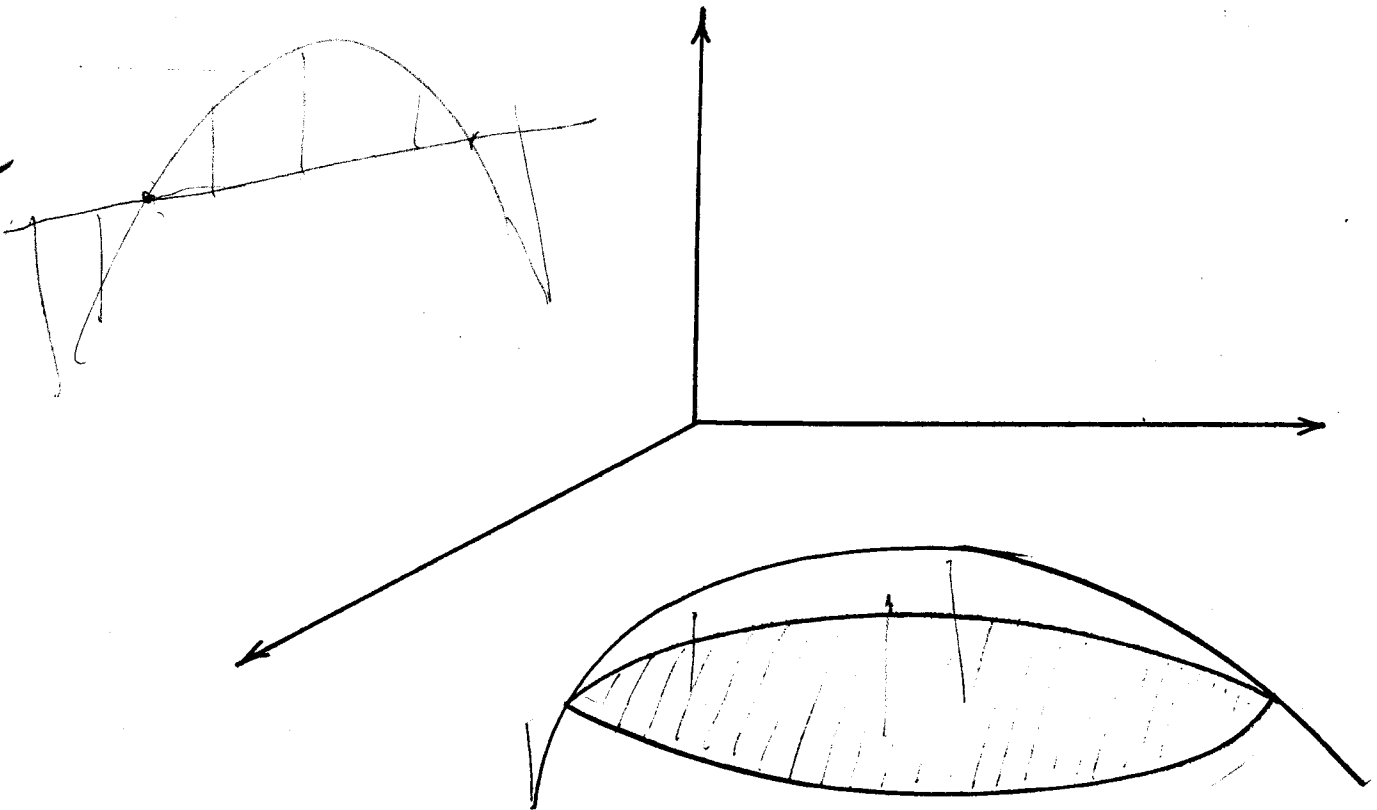
$$\nabla_\lambda L(x, \lambda) = g(x) = 0$$

## Constrained Optimization: Inequality Constraints

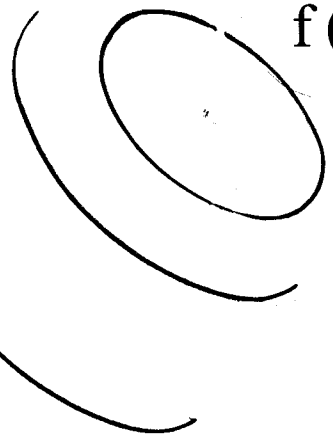
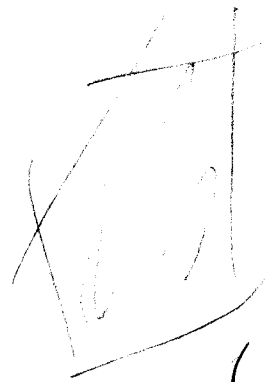
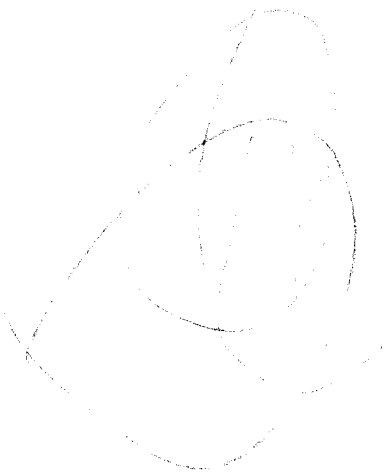
$$f(x) \rightarrow \min$$

$$c_i(x) \geq 0, \quad i = 1, \dots, m$$

$c_i(x)$  - concave

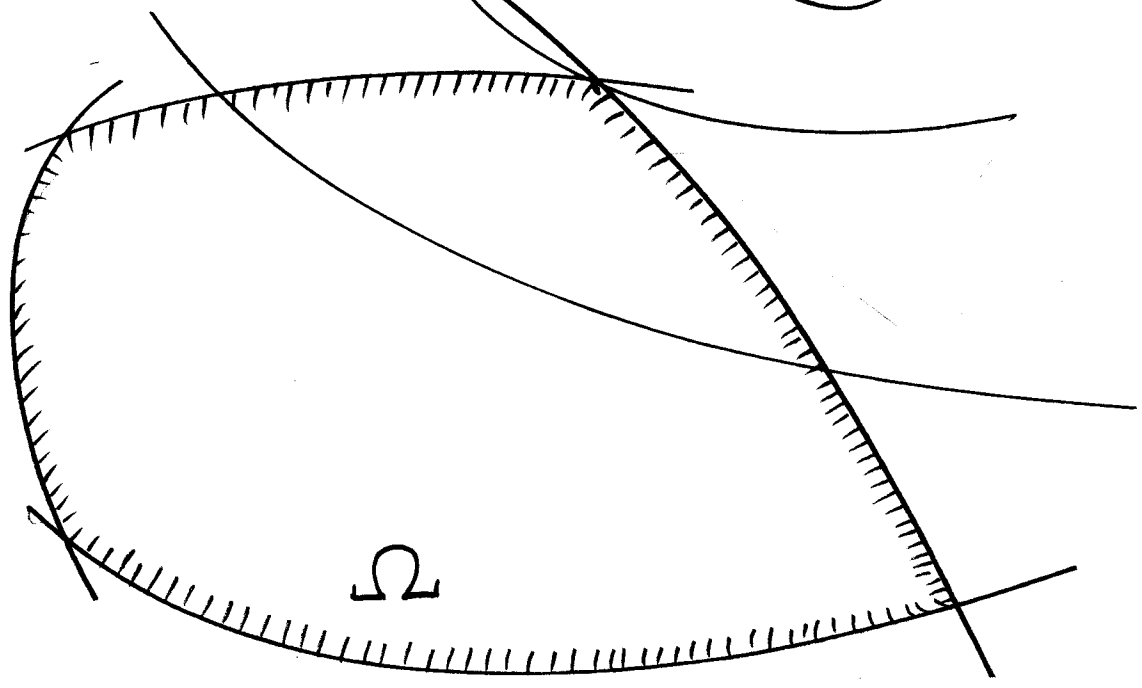


$$x : c(x) \geq 0$$

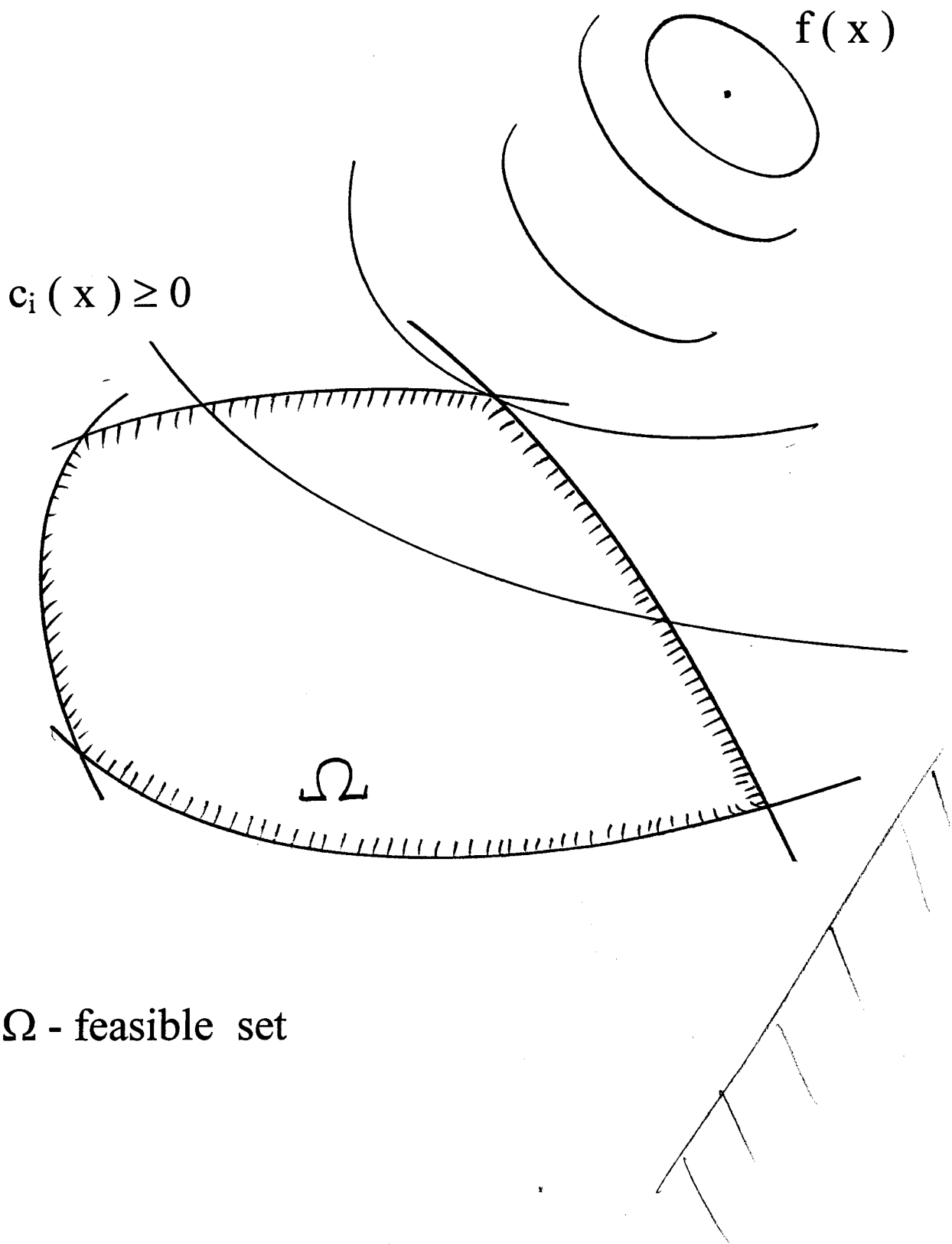


$f(x)$

$x: c_i(x) \geq 0$



$\Omega$  - feasible set



$$c_i(x) \geq 0$$

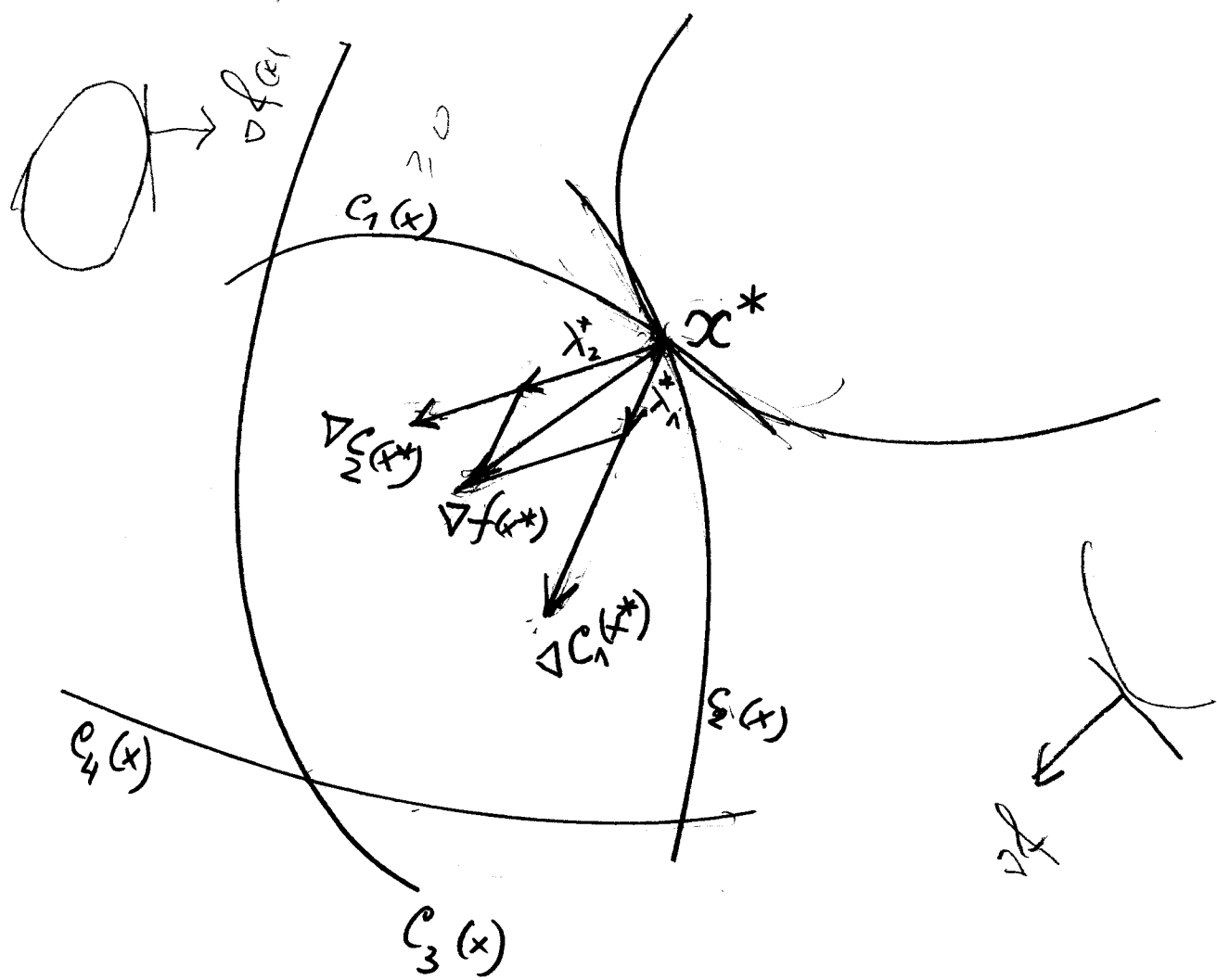
$f(x)$

$\Omega$

$\Omega$  - feasible set

$f(x) = 10x^2$

$$\nabla f(x) = \begin{pmatrix} 20x \\ 0 \end{pmatrix}$$



$$\nabla f(x^*) = \lambda_1^* \nabla c_1(x^*) + \lambda_2^* \nabla c_2(x^*)$$

Let  $\lambda_3^* = 0, \lambda_4^* = 0$

$$\nabla f(x^*) = \sum_{i=1}^4 \lambda_i^* \nabla c_i(x^*)$$

$$\lambda_i^* \geq 0, \quad c_i(x^*) \geq 0$$

$$\lambda_i^* c_i(x^*) = 0, \quad i = 1, \dots, m$$

$$\nabla f(x^*) - \sum \lambda_i^* \nabla c_i(x^*) = 0$$

or

$$L(x, \lambda) = f(x) - \sum \lambda_i c_i(x)$$

$$\nabla_x L(x^*, \lambda^*) = \nabla f(x^*) - \sum \lambda_i^* \nabla c_i(x^*) = 0$$

$$\nabla_{\lambda} L(x^*, \lambda^*) = -c(x^*) \leq 0$$

$$\lambda_i^* \cdot c_i(x^*) = 0$$

## Optimality Condition

Karush – Kuhn – Tucker's condition

$$L(x, \lambda) = f(x) - \sum \lambda_i c_i(x)$$

$$\left\{ \begin{array}{l} \nabla_x L(x^*, \lambda^*) = 0 \\ \nabla_\lambda L(x^*, \lambda^*) = -c(x^*) \leq 0 \\ \lambda^{*T} c(x^*) = 0 \end{array} \right.$$



$$\begin{aligned}
 & f(x) \rightarrow \min \\
 & c_i(x) \geq 0, \quad i = 1, \dots, m \\
 & x_j \geq 0, \quad j = 1, \dots, n
 \end{aligned}$$

$$L(x, \lambda) = f(x) - \sum \lambda_i c_i(x)$$

$$\frac{\partial L(x, \lambda)}{\partial x_j} = \frac{\partial f(x)}{\partial x_j} - \sum \lambda_i \frac{\partial c_i(x)}{\partial x_j} \geq 0, \quad j = 1, \dots, n$$

$$x_j \cdot \frac{\partial L}{\partial x_j} = 0$$

$$\frac{\partial L(x, \lambda)}{\partial \lambda_i} = -c_i(x) \leq 0, \quad i = 1, \dots, m$$

$$\lambda_i \cdot \frac{\partial L}{\partial \lambda_i} = 0$$

$$f(x_1, x_2) = e^{x_1} - \ln(x_2 + 3)$$

$$2x_1 + 5x_2 \leq 10$$

$$3x_1 + x_2 \leq 3$$

$$x_1 \geq 0, x_2 \geq 0$$

$$L(x, \lambda) = e^{x_1} - \ln(x_2 + 3) - \lambda_1(10 - 2x_1 - 5x_2) \\ - \lambda_2(3 - 3x_1 - x_2)$$

$e^{x_1}$  - convex because

$$\left(e^{x_1}\right)' = e^{x_1}, \quad \left(e^{x_1}\right)'' = e^{x_1} > 0$$

$$\left(\ln(x_2 + 3)\right)' = \frac{1}{x_2 + 3}$$

$$\left(\ln(x_2 + 3)\right)'' = -\frac{1}{(x_2 + 3)^2} < 0$$

$$(-\ln(x_2 + 3))'' > 0$$

$f(x_1, x_2)$  - convex

$e^{x_1}$  - monoton. increasing

$-\ln(x_2 + 3)$  - monoton. decreasing

$$x_1 = 0, \quad x_2 = 2, \quad \lambda_1 = ? \quad \lambda_2 = 0$$

$$\nabla_{x_1} L = e^{x_1} + 2\lambda_1 + 3\lambda_2 \geq 0$$

$$\nabla_{x_2} L = -\frac{1}{x_2 + 3} + 5\lambda_1 + \lambda_2 = 0$$

$$1 + 2\lambda_1 + 3\lambda_2 \geq 0$$

$$-\frac{1}{5} + 5\lambda_1 + \lambda_2 = 0$$

$$\lambda_1 = \frac{1}{25}$$

$x = (0, 2)$  is the optimal point

Since  $\lambda_1 = \frac{1}{25} > 0$ , the constraint  $x_1 = 0$  is active at the optimal point.

The complementary slackness condition is not satisfied.