

Non-Linear Optimization

K units of capital, L units of labor, KL units of goods

Capital can be purchased \$4k/unit
Labor \$1k/unit

Total of \$8k is available

How can the firm maximize the output?

$$z = KL \rightarrow \max$$

$$4K + L \leq 8$$

$$K \geq 0, L \geq 0$$

Consider the LP

$$\begin{aligned} (c, x) &\rightarrow \max \\ Ax &\leq b \\ x &\geq 0 \end{aligned}$$

c is independent on x

More realistic approach $c(x)$

Then

$$\begin{aligned} z = (c(x), x) &\rightarrow \max \\ Ax &\leq b \\ x &\geq 0 \end{aligned}$$

Market Problem

$$p = (p_1, \dots, p_n)$$

1) $p \in R_{++}^n$ is a positive vector of products on the market

2) m consumers: each consumer has his own vector of preferences

$$a_i^T = (a_{i1}, \dots, a_{in}), 0 \leq a_{ij} \leq 1 \text{ and a budget } b_i > 0$$

$$b^T = (b_1, \dots, b_m) \in R_{++}^m$$

Matrix of Preferences

$$A = \begin{array}{|ccccc|} \hline a_{11} & \dots & a_{1j} & \dots & a_{1n} \\ \vdots & & \vdots & & \vdots \\ a_{i1} & \dots & a_{ij} & \dots & a_{in} \\ \vdots & & \vdots & & \vdots \\ a_{m1} & \dots & a_{mj} & \dots & a_{mn} \\ \hline \end{array}$$

Each row and each column has at least one

$$a_{ij} > 0 \quad (*)$$

If there is a row with $a_{ij} = 0, \forall j$ then the consumer i is not interested in the market

If there is a column j with $a_{ij} = 0, \forall i$ then nobody is interested in the product j

3) For consumer i we introduce the consumptions vector

$$x_i^T = (x_{i1}, \dots, x_{in}) \in R_+^n.$$

The components x_{ij} show how much of product j consumer i is going to buy.

4) With each consumer we associate utility function

$$u_i(x_i) = (a_i, x_i) = \sum_{j=1}^n a_{ij}x_{ij}$$

5) Each consumer will maximize the utility function within the budget available.

If $\pi = (\pi_1, \dots, \pi_n)$ is the vector of prices for the products then each consumer will solve the following LP problem

$$x_i^*(\pi) = \operatorname{argmax}\{u_i(x_i) / (\pi, x_i) \leq b_i, x_i \geq 0\}$$

The total demand

$$x^*(\pi) = \sum_{i=1}^m x_i^*(\pi)$$

while the supply is p

Question: Is there such $\pi^* = (\pi_1^*, \dots, \pi_n^*)$ that

$$x^*(\pi^*) = p$$

Equilibrium

D.GALE "The theory of Linear Economic
Models" 1960

YES !!

For any budget vector $b \in R_{++}^m$, any supply vector $p \in R_{++}^n$ and any matrix of preferences A with property (*) the equilibrium exists

Consider the following convex programming problem

$$f(x) = \sum_{i=1}^m b_i \ln(a_i, x_i) \rightarrow \max \quad (1)$$

$$\sum_{i=1}^m x_i \leq p$$

and

$$x_i \in R_+^n$$

or

$$f(x) = \sum_{i=1}^m b_i \ln\left(\sum_{j=1}^m a_{ij} x_{ij}\right) \rightarrow \max$$

$$\sum_{i=1}^m x_{ij} \leq p_j$$

$$x_{ij} \geq 0, i = 1, \dots, m; j = 1, \dots, n$$

TARTALIA PROBLEM (1500 – 1557)

One has to divide 8 in two parts, that the sum of their product and their difference will be max.

$$x + y = 8, \quad x > 0, \quad y > 0$$

$$z = xy + (x - y) \rightarrow \max$$

$$y = 8 - x$$

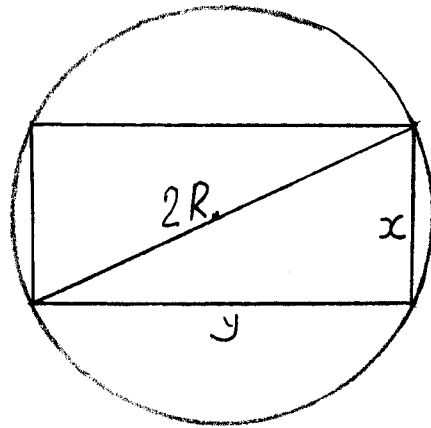
$$z = x(8 - x) + (2x - 8) \rightarrow \max$$

$$x \geq 0$$

$$z'_x = 10 - 2x = 0$$

$$x = 5, \quad y = 3$$

Inscribe rectangle with max area in a circle with a given radius R



$$z = xy \rightarrow \max$$

$$y = \sqrt{4R^2 - x^2}$$

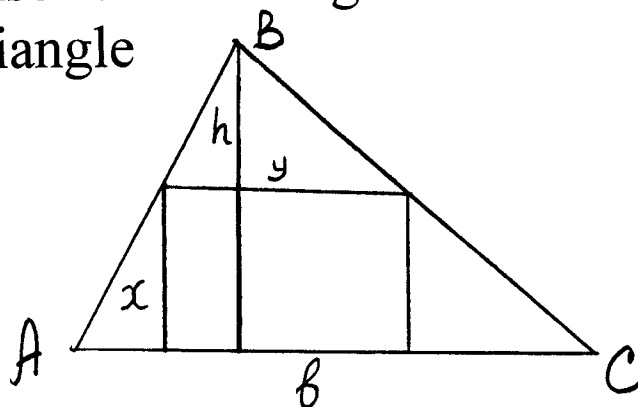
$$z = x \sqrt{4R^2 - x^2} \rightarrow \max$$

$$z' = \sqrt{4R^2 - x^2} + x \frac{1}{2} \frac{-2x}{\sqrt{4R^2 - x^2}}$$

$$= \frac{4R^2 - 2x^2}{\sqrt{4R^2 - x^2}} = 0$$

$$x = R \sqrt{2}, \quad y = R \sqrt{2}$$

Inscribed rectangle with max area in a given triangle



$$z = xy$$

$$\frac{h}{H} = \frac{y}{b}, \quad h = H - x$$

$$\frac{H - x}{H} = \frac{y}{b}, \quad y = \frac{b}{H} (H - x)$$

$$z = \frac{b}{H} \cdot x(H - x) \rightarrow \max$$

$$x \geq 0$$

$$[x(H - x)]'_x = H - 2x = 0$$

$$x = \frac{H}{2}$$

$$y = \frac{b}{H} \left(H - \frac{H}{2} \right) = \frac{b}{2} \quad z^* = \frac{Hb}{4}$$

$$\max x_1 \dots x_n$$

$$x_1 + \dots + x_n = 1$$

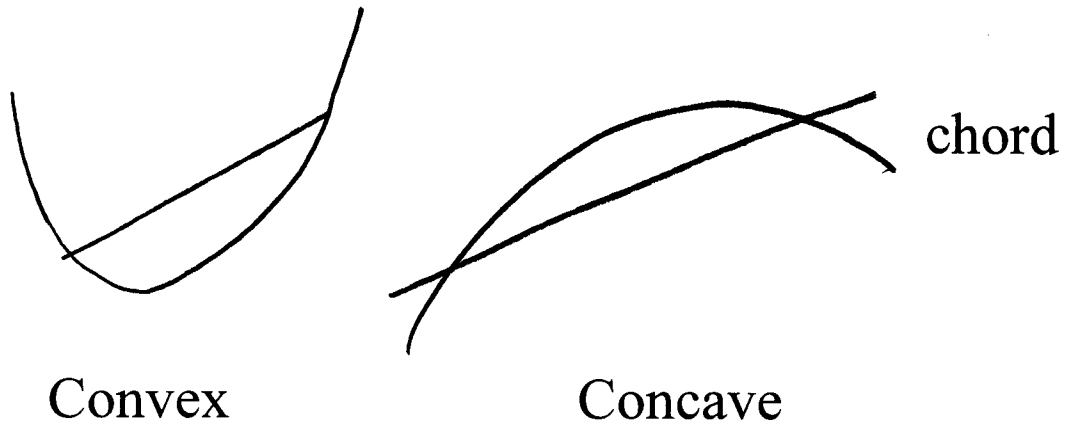
$$x_i \geq 0$$

$${}^n\sqrt{x_1 \dots x_n} \leq \frac{x_1 + \dots + x_n}{n}$$

$$x_1 = \dots = x_n \quad x_i = \frac{1}{n}$$

$$\max x_1 \dots x_n = n^{-n}$$

Convex and Concave Functions

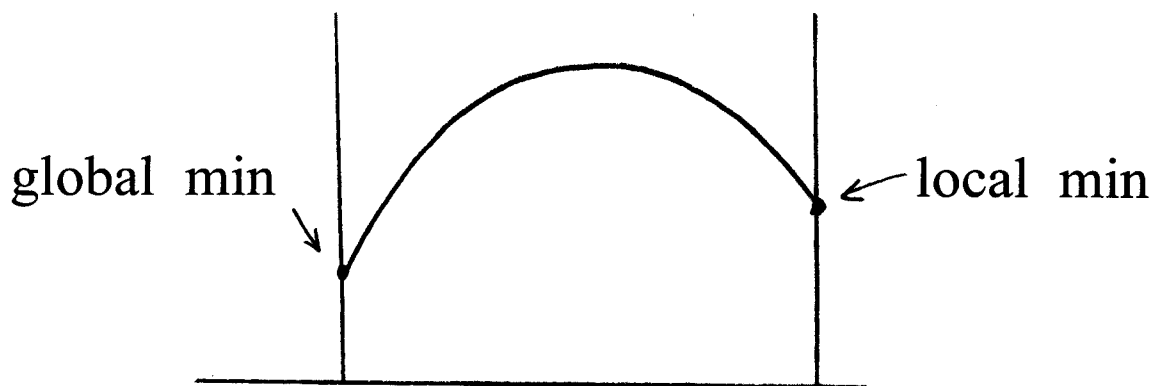


$$f(\lambda x_1 + (1 - \lambda)x_2) \leq \lambda f(x_1) + (1 - \lambda)f(x_2)$$

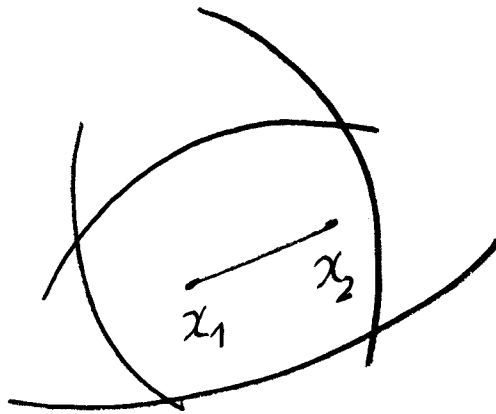
Convex

\geq Concave

local min convex $f(x) =$ global min $f(x)$



Convex Set

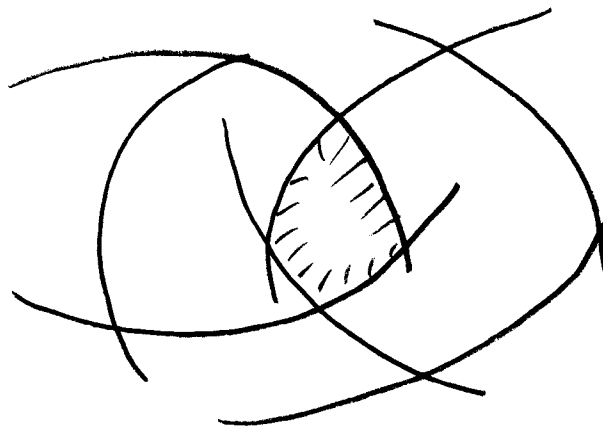


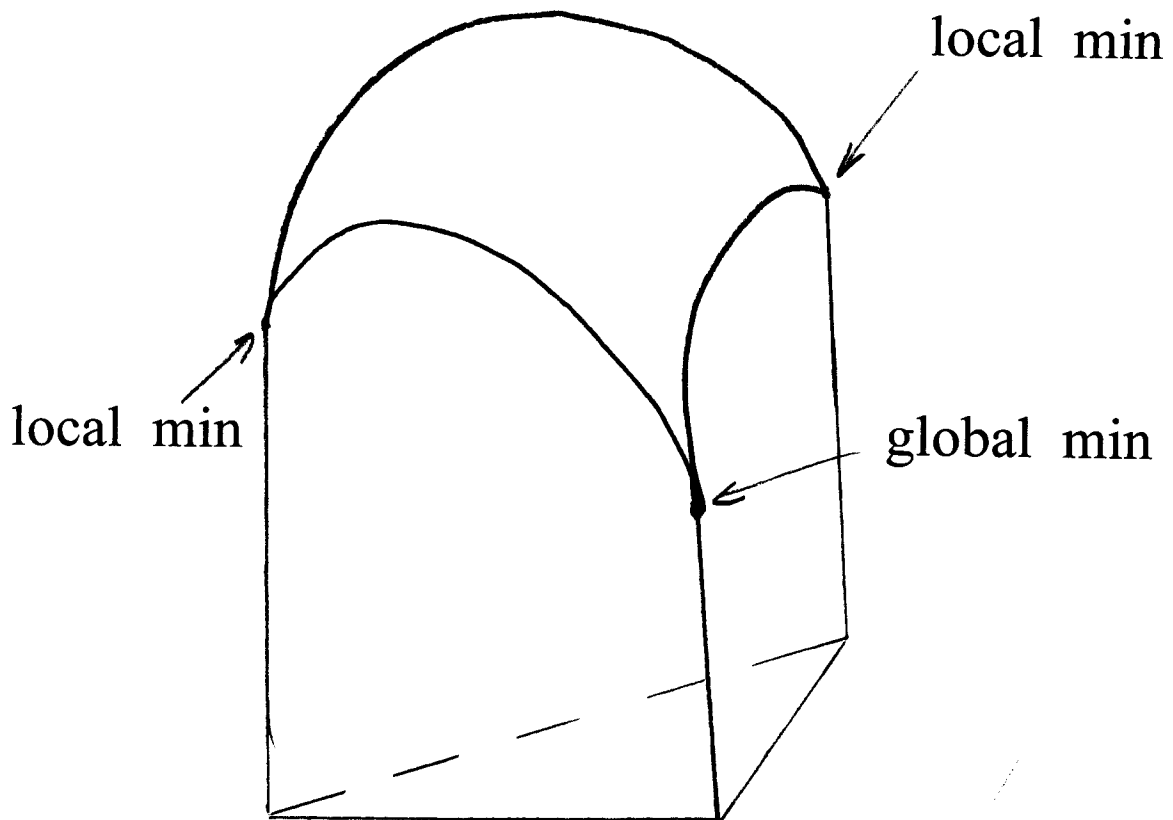
Ω is convex if

$$\forall x_1, x_2 \in \Omega \Rightarrow x = (1 - \lambda)x_1 + \lambda x_2 \in \Omega$$
$$0 < \lambda < 1$$

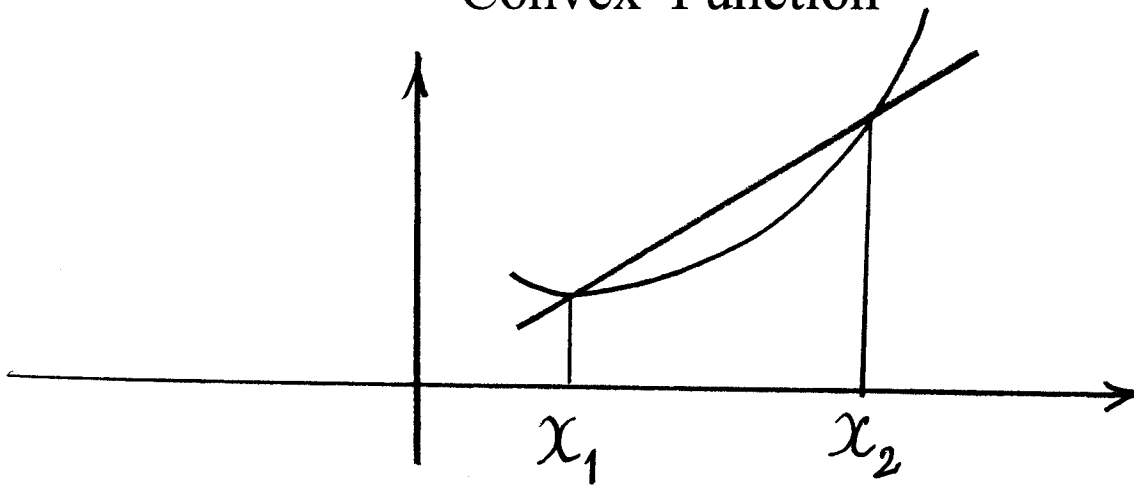
if Ω_i is convex then

$\Omega = \prod \Omega_i$ is convex





Convex Function

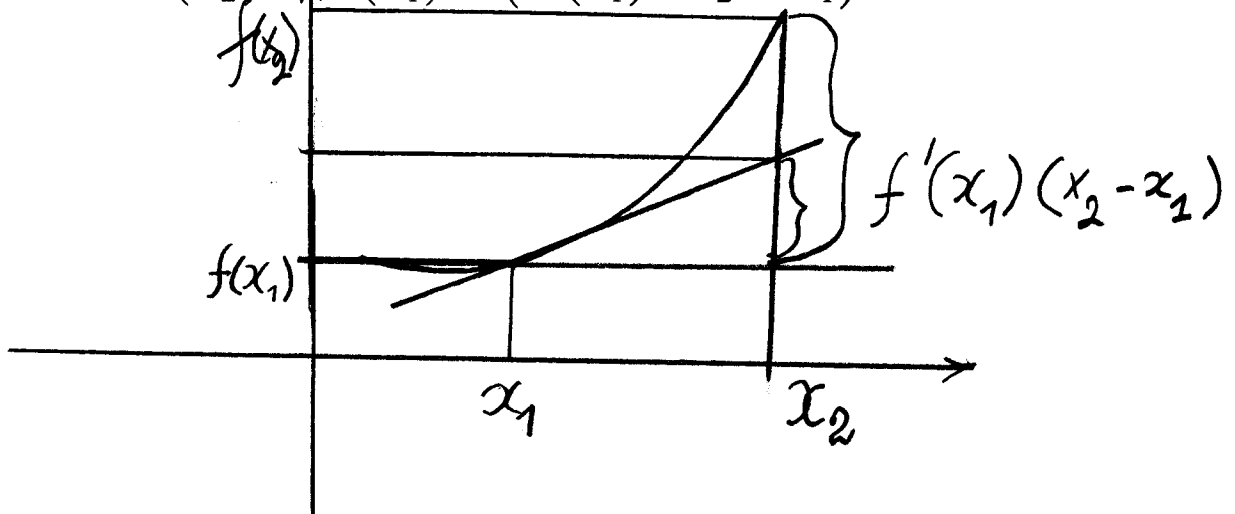


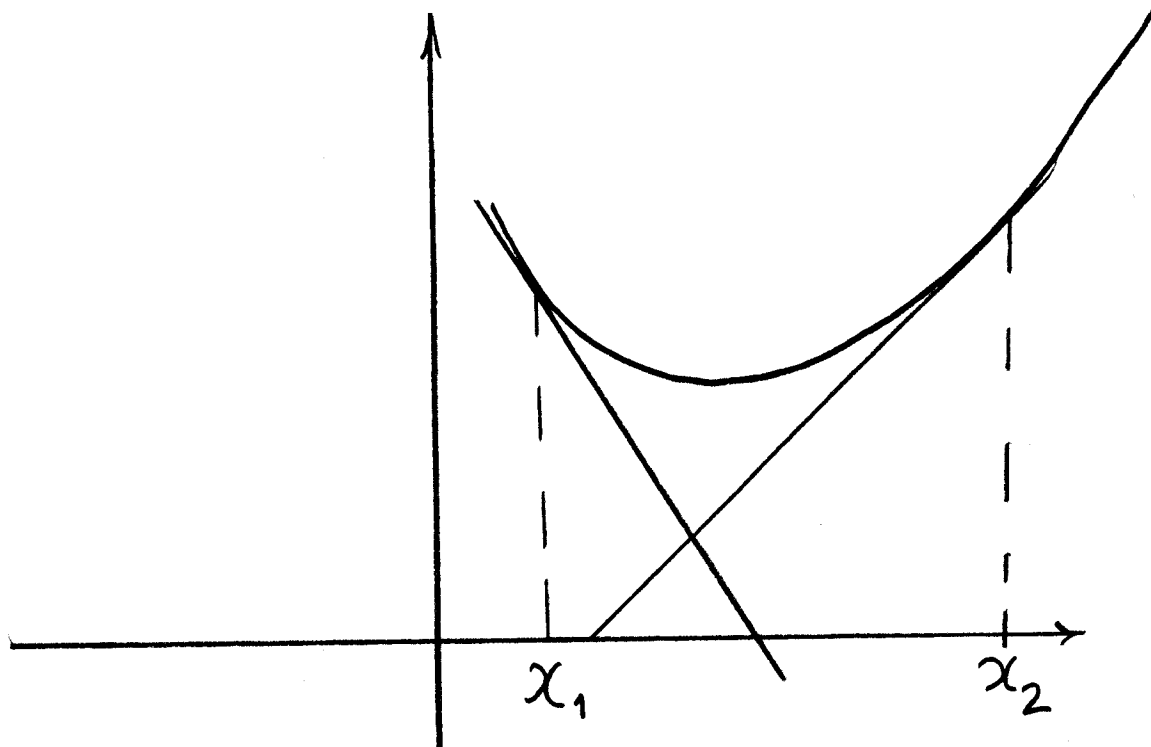
$$1. f((1-\lambda)x_1 + \lambda x_2) \leq (1-\lambda)f(x_1) + \lambda f(x_2)$$

Gradient

$$\nabla f(x) = \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right)$$

$$2. f(x_2) - f(x_1) \geq (f'(x_1), x_2 - x_1)$$





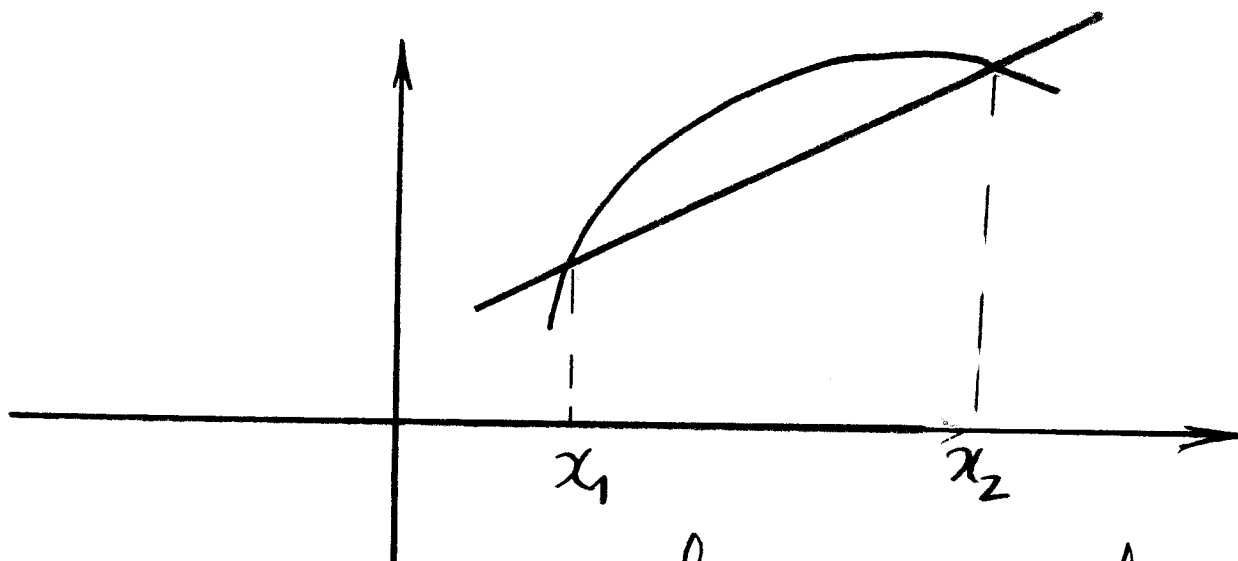
$$3. (\nabla f(x_1) - \nabla f(x_2), x_1 - x_2) \geq 0$$

Hessian

$$\nabla_{xx}^2 f(x) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1 \partial x_1}, \dots, \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_n \partial x_1}, \dots, \frac{\partial^2 f}{\partial x_n \partial x_n} \end{bmatrix}$$

$$4. (\nabla_{xx}^2 f(x)y, y) \geq m(y, y)$$

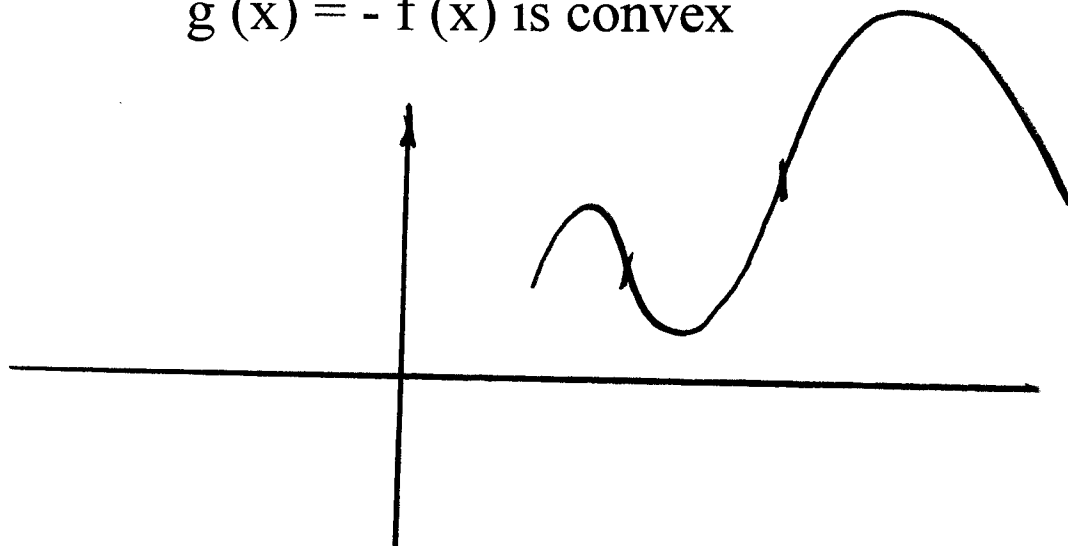
Concave Functions



$$f((1-\lambda)x_1 + \lambda x_2) \geq (1-\lambda)f(x_1) + \lambda f(x_2)$$

$f(x)$ is concave if

$g(x) = -f(x)$ is convex



Neither convex nor concave

Linear-Function

$f(x) = ax + b$
is both convex and concave

Examples

1) $f_1(x) = x^3$

2) $f_2(x) = \frac{1}{x}$

3) $f_3(x) = \ln x$

4) $f(x_1, x_2) = x_1^3 + 3x_1x_2 + x_2^2,$

$$\nabla f(x) = \begin{pmatrix} 3x_1^2 + 3x_2 \\ 3x_1 + 2x_2 \end{pmatrix}$$

$$H(x) = \begin{pmatrix} 6x_1 & 3 \\ 3 & 2 \end{pmatrix}$$

$$x_1 > 0,$$

$$6x_1 \cdot 2 - 9 \geq 0$$

$$x_1 \geq \frac{3}{4}$$

1) If $f(x)$ is convex then

$\Omega = \{x: f(x) \leq c\}$ is convex for any c

2) If $f_i(x)$ is convex and $\alpha_i \geq 0$ then

$f(x) = \sum_{i=1}^m \alpha_i f_i(x)$ is convex

3) If $y = f(x)$ concave and $f(x) > 0$ then

$Z = \frac{1}{f(x)}$ is convex

4) If $y = f(x) \geq 0$ and concave then

$Z = \ln f(x)$ is concave

Unconstrained Optimization

$$\min f(x) = f(x^*)$$

or

$$x^* = \text{arg min} \{f(x) / x \in R^h\}$$

Two basic methods

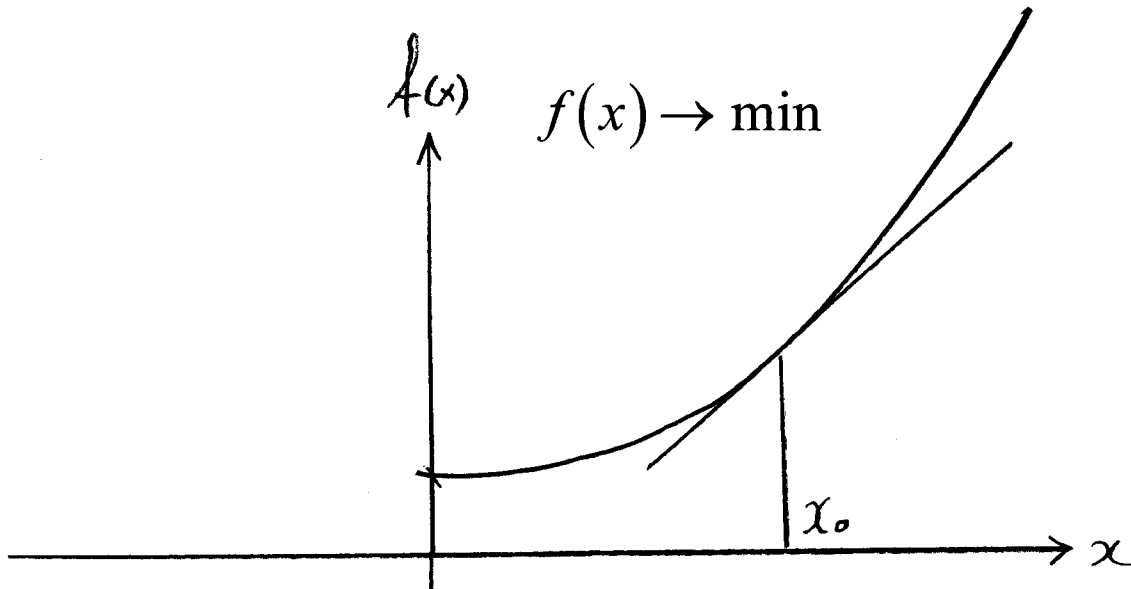
Gradient Method

$$x^{s+1} = x^s - t \nabla f(x^s), \quad t > 0$$

Newton Method

$$x^{s+1} = x^s - \left(\nabla_{xx}^2 f(x^s) \right)^{-1} \nabla f(x^s)$$

Unconstrained minimization

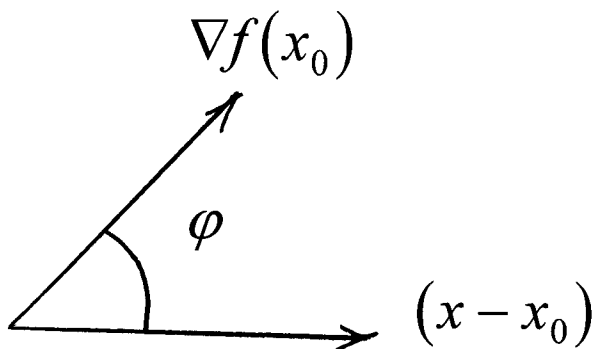


$$\tilde{f}(x) \approx f(x_0) + \nabla f^T(x_0)(x - x_0)$$

$$\nabla f(x) = \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right)$$

$$\min \tilde{f}(x)$$

$$\|x - x_0\| \leq 1$$



$$\nabla f^T(x^0)(x - x^0) = \|\nabla f(x_0)\| \|x - x_0\| \cos \varphi$$

$$\varphi = 180^\circ$$

$$x - x^0 = - \frac{\nabla f(x_0)}{\|\nabla f(x_0)\|}$$

$$x^1 = x^0 - t \frac{\nabla f(x_0)}{\|\nabla f(x_0)\|}$$

$$\min \tilde{f}(x)$$

$$x : \quad \|x - x^0\| \leq 1 \quad \quad \quad \|x\| = (x_1^2 + \dots + x_n^2)^{\frac{1}{2}}$$

then we are dealing with the following problem

$$\begin{aligned} \min & (\nabla f(x^0), \zeta) \\ & \|\zeta\| = 1 \end{aligned}$$

$$(\nabla f(x^0), \zeta) = \|\nabla f(x^0)\| \|\zeta\| \cos \varphi$$

$$\zeta = - \frac{\nabla f(x^0)}{\|\nabla f(x^0)\|}$$

This is the steepest descent direction

*Another way of looking on this matter
is the following*

Let consider the function

$$f(x^0 + t\zeta)$$

$$\begin{aligned} \frac{d}{dt} f(x^0 + t\zeta) &= (\nabla f(x^0 + t\zeta), \zeta) \quad / t = 0 \\ &= (\nabla f(x^0), \zeta) \end{aligned}$$

The value $(\nabla f(x^0), \zeta)$ characterizes the velocity of the function increase or decrease in the direction ζ . Again increase or decrease will depend on the angle between $\nabla f(x^0)$ and ζ .

$$\min (\nabla f(x^0), \zeta) \Rightarrow \zeta = - \frac{\nabla f(x^0)}{\|\nabla f(x^0)\|}$$

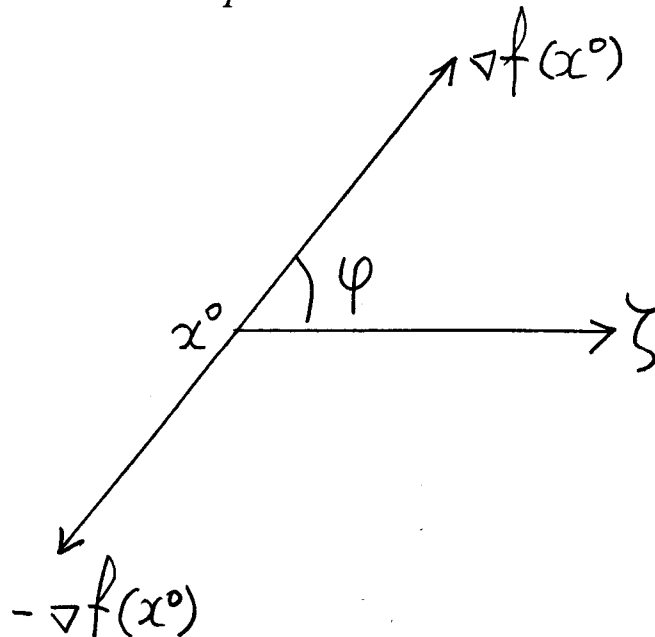
$$\|\zeta\| \leq 1$$

$$x^{s+1} = x^s - t \nabla f(x^s)$$

$$t_{s+1} = \text{avg min}_{t \geq 0} f(x^s - t \nabla f(x^s))$$

$$= (\nabla f(x^s - t \nabla f(x^s)), \nabla f(x^s)) = 0$$

Steepest descent



$$(\nabla f(x) - \nabla f(y), x - y) \geq m \|x - y\|$$

$$\|\nabla f(x) - \nabla f(y)\| \leq L \|x - y\|$$

$$x^{s+1} = x^s - t\nabla f(x^s)$$

$$x^{s+1} - x^* = x^s - x^* - t\nabla f(x^s)$$

$$(x^{s+1} - x^*, x^{s+1} - x^*) = (x^s - x^* - t\nabla f(x^s), x^s - x^* - t\nabla f(x^s))$$

$$\begin{aligned} \|x^{s+1} - x^*\|^2 &= (x^s - x^*, x^s - x^*) \\ &\quad - 2t(x^s - x^*, \nabla f(x^s) - \nabla f(x^*)) \\ &\quad + t^2 \|\nabla f(x^s) - \nabla f(x^*)\|^2 \end{aligned}$$

$$= \|x^s - x^*\|^2 - 2tm \|x^s - x^*\|^2 + t^2 L^2 \|x^s - x^*\|^2$$

$$= \|x^s - x^*\| (1 - 2tm + t^2 L^2)$$

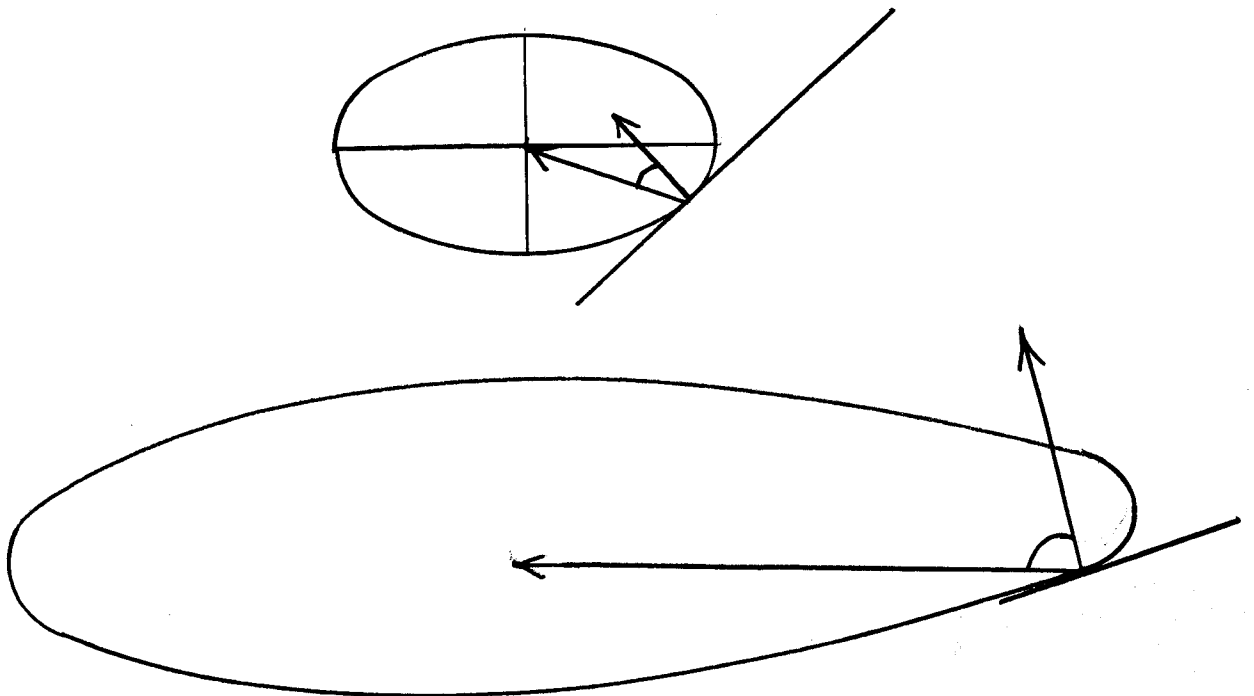
$$q(t) = 1 - 2tm + t^2 L^2 \rightarrow \min_t$$

$$-2m + 2tL^2 = 0$$

$$t = \frac{m}{L^2}$$

$$q\left(\frac{m}{L^2}\right) = 1 - \frac{m}{L^2}$$

$$\|x^{s+1} - x^*\| \leq \sqrt{1 - \frac{m}{L^2}} \cdot \|x^s - x^*\|$$



Cauchy 1847

Steepest descent

$$t_{s+1} : \min_t f(x^s - t \nabla f(x^s))$$

$$x^{s+1} = x^s - t_{s+1} \nabla f(x^s)$$

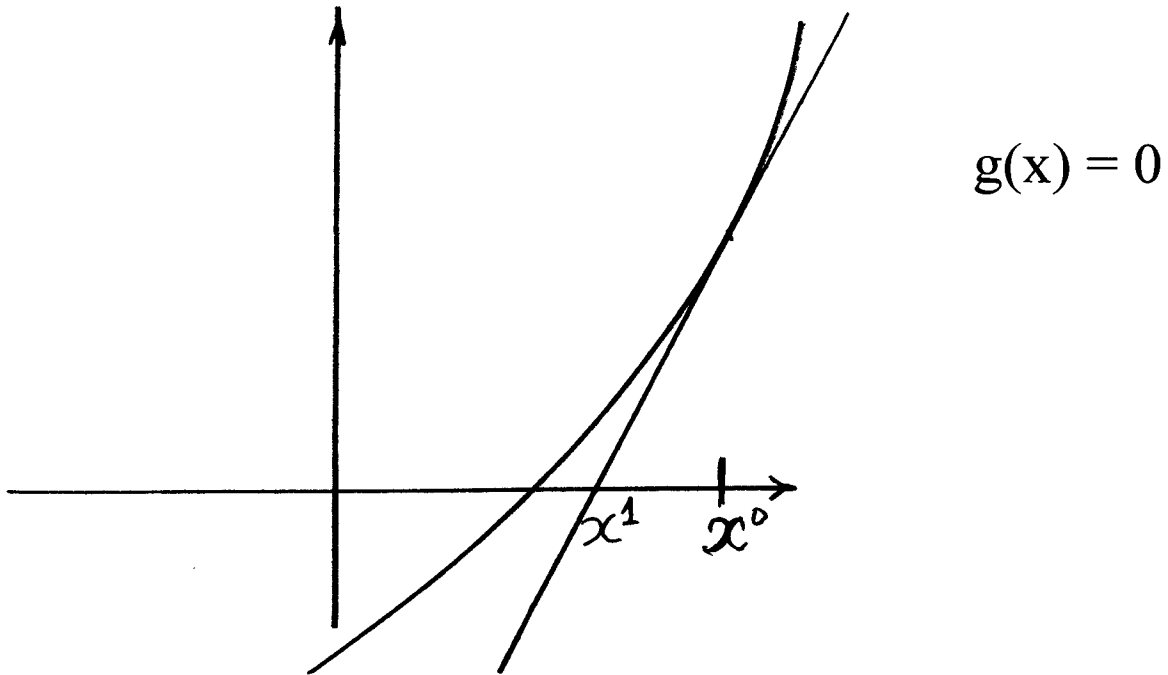
$$q = \sqrt{\frac{L-m}{L+m}} = \sqrt{\frac{1-\sigma}{1+\sigma}}$$

$\sigma = \frac{m}{L}$ – condition number of the unconstr.

If $\sigma > 0$ is small then

the unconstr. optimization problem is

ill – conditioned

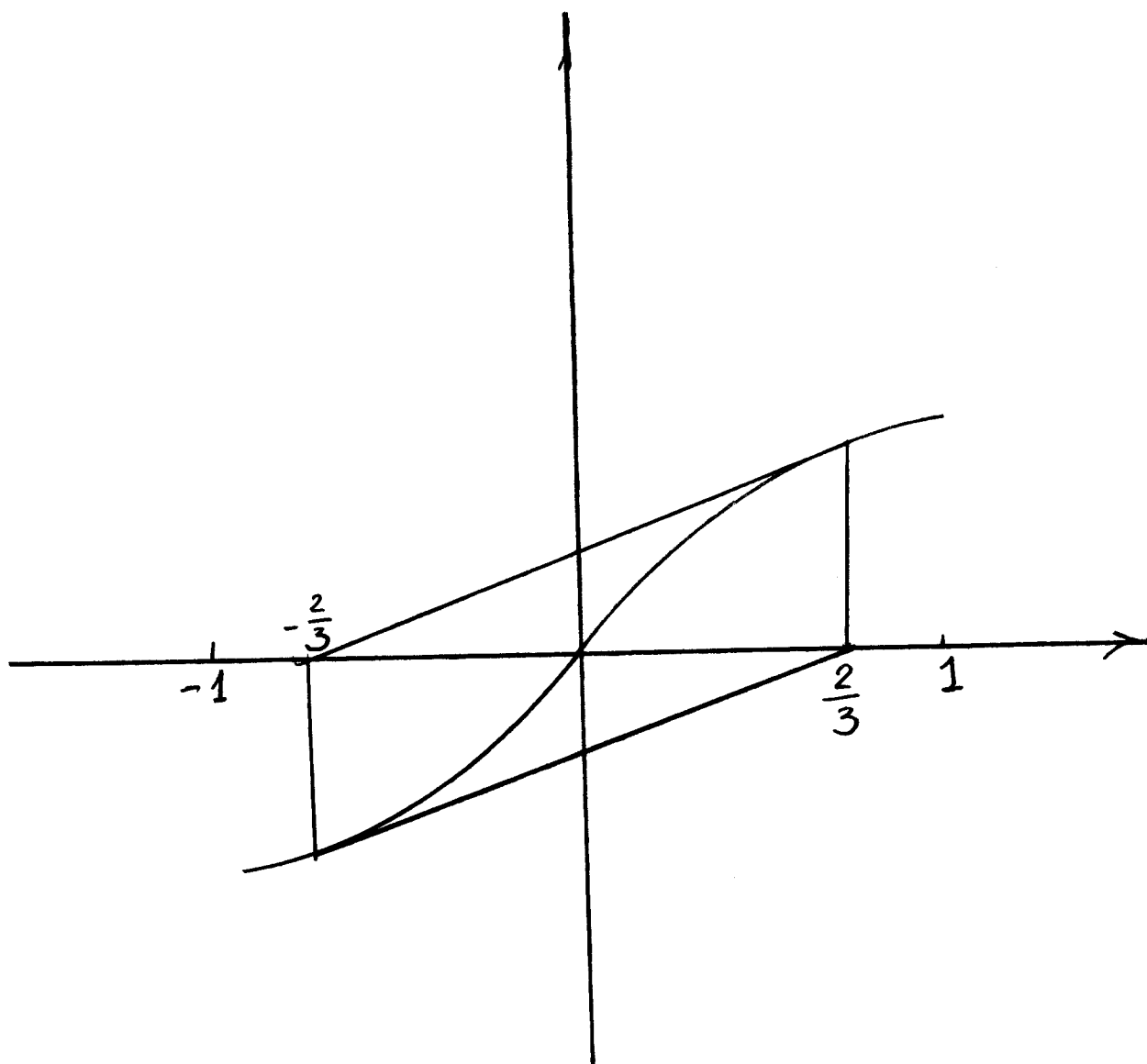


$$0 = g(x_0 + \Delta x) = g(x_0) + g'(x_0)(x - x_0)$$

$$x - x_0 = -(g'(x_0))^{-1} g(x_0)$$

$$x_1 = x_0 - (g'(x_0))^{-1} g(x_0)$$

$$x_{s+1} = x_s - (g'(x_s))^{-1} g(x_s)$$

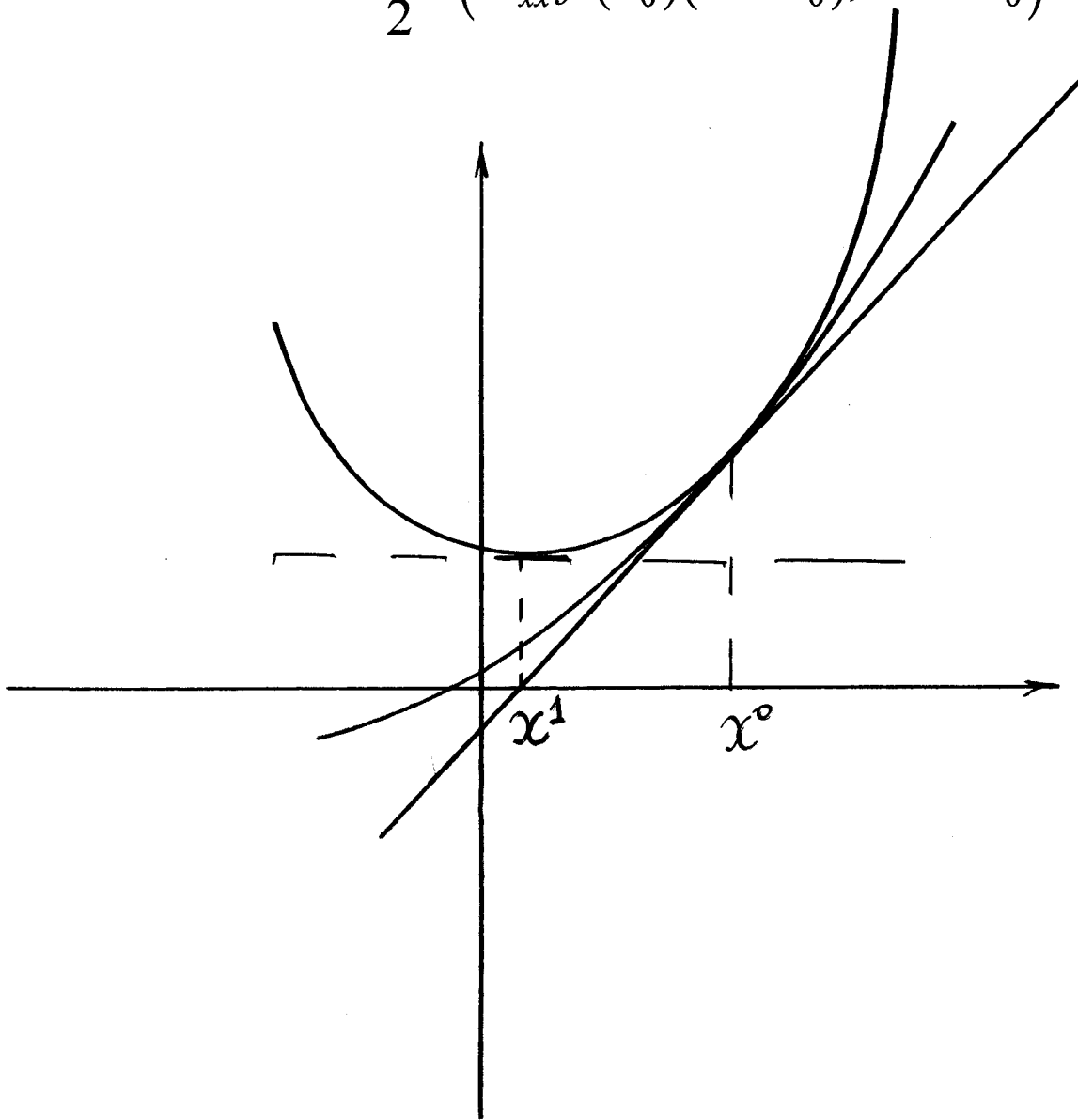


$$g(x) = \begin{cases} -(x-1)^2 + 1, & 0 \leq x \leq 1 \\ (x+1)^2 - 1, & -1 \leq x \leq 0 \end{cases}$$

$$f(x) \rightarrow \min \Leftrightarrow \nabla f(x) = g(x) = 0$$

$$\tilde{f}(x) = f(x_0) + (\nabla f(x_0), x - x_0)$$

$$+ \frac{1}{2} (\nabla_{xx}^2 f(x_0)(x - x_0), x - x_0)$$



$$\min \tilde{f}(x) \Rightarrow \nabla \tilde{f}(x) = 0$$

$$\nabla \tilde{f}(x) = \nabla f(x_0) + \nabla_{xx}^2 f(x_0)(x - x_0)$$

$$x - x_0 = -\left(\nabla_{xx}^2 f(x_0)\right)^{-1} \nabla f(x_0)$$

$$x_1 = x_0 - \left(\nabla_{xx}^2 f(x_0)\right)^{-1} \nabla f(x_0)$$

or

$$x_{s+1} = x_s - \left(\nabla_{xx}^2 f(x_s)\right)^{-1} \nabla f(x_s)$$

$$\|x^{s+1} - x^*\| \leq c \|x^s - x^*\|^2$$

$$x^{s+1} = x^s - \nabla^2 f^{-1}(x^s) \nabla f(x^s)$$

$$x^{s+1} - x^* = x^s - x^* - \nabla^2 f^{-1}(x^s) \nabla f(x^s)$$

$$\begin{aligned} \|x^{s+1} - x^*\|^2 &= \left(x^{s+1} - x^*, x^s - x^* - \nabla^2 f^{-1}(x^s) \nabla f(x^s) \right) \\ &\leq \left(x^{s+1} - x^*, x^s - x^* - \nabla^2 f^{-1}(x^s) (\nabla f(x^s) - \nabla f(x^*)) \right) \\ &= \left(x^{s+1} - x^*, \nabla^2 f^{-1}(x^s) (\nabla^2 f(x^s)(x^s - x^*) \right. \\ &\quad \left. - \nabla f(x^s) - \nabla f(x^*)) \right) \\ &= \left(x^{s+1} - x^*, \nabla^2 f^{-1}(x^s) (\nabla^2 f(x^s)(x^s - x^*) \right. \\ &\quad \left. - \nabla^2 f(x^s + \theta(x^* - x^s))(x^s - x^*)) \right) \\ &= \left(x^{s+1} - x^*, \nabla^2 f^{-1}(x^s) (\nabla^2 f(x^s) \right. \\ &\quad \left. - \nabla^2 f(x^s + \theta(x^* - x^s))) (x^s - x^*) \right) \end{aligned}$$

$$(\nabla^2 f(x)\zeta, \zeta) \geq m(\zeta, \zeta)$$

$$\|\nabla^2 f(x) - \nabla^2 f(y)\| \leq L \|x - y\|$$

$$\|x^{s+1} - x^*\|^2$$

$$\leq \|\nabla^2 f^{-1}(x^s)\| \|\nabla^2 f(x^s) - \nabla^2 f(x^s + \theta(x^* - x^s))\|$$

$$\|x^{s+1} - x^*\| \|x^s - x^*\|$$

$$\|x^{s+1} - x^*\| \leq m^{-1}L \|x^s - (x^s - \theta(x^* - x^s))\| \|x^s - x^*\|$$

$$= m^{-1}L\theta \|x^s - x^*\|^2$$

$$\|x^{s+1} - x^*\| \leq c \|x^s - x^*\|^2$$

$$c = m^{-1}L\theta$$